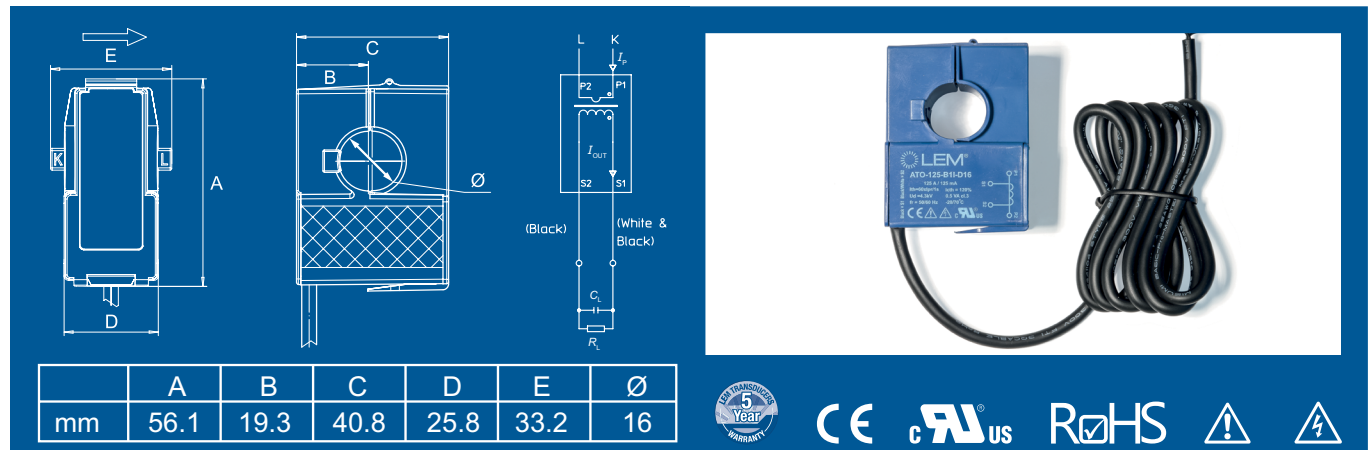


Ref: ATO-125-B1I-D16

ATO series is a split core current transformer for the electronic measurement of AC waveform current with galvanic separation between the primary circuit (power) and the secondary circuit (measurement).

ATO series is an ideal current transformer for new Smart-Grid applications, in which ratio error and phase displacement are fully tested with IEC 61869 standards accordance.

Accuracy Class 3



Features

- Split-core current transformer
- Rated primary current: 125 A
- Application up to 600 V CAT III PD2, basic insulation
- Accuracy class 3 (IEC 61869-2)
- Current output: 125 mA at I_{Pr}
- Ø 16 mm sensing aperture
- 1 m output cable
- Ambient temperature -20 °C ... +70 °C
- Slot for attaching the current transform on the primary with plastic tie
- DIN rail adapter (optional).

Advantages

- No interruption of electricity during installation on insulated conductors
- Quick, non-intrusive and easy setup
- Provide a calibrate output.

Applications

- Hybrid inverter (Home Energy Storage)
- Power metering: current measurement for active power calculation
- Building sub-metering: energy efficiency monitoring, consumption analysis and cost allocation
- Power quality monitoring: electrical loads and distribution system equipment
- Distributed measurement systems
- Condition monitoring (e.g. Motor loads such as conveyers, pumps).

Standards

- IEC 61010-1: 2010
- IEC 61010-031 ed1.1: 2012
- IEC 61869-1 ed1.0: 2007
- IEC 61869-2: ed1.0: 2012
- IEC 61869-6: draft 2016
- IEC 61869-10: draft 2016
- UL 508: 2013.

N°52.C3.36.000.0

19May2017/version 1

LEM reserves the right to carry out modifications on its transducers, in order to improve them, without prior notice

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Absolute maximum ratings

| Parameter | Symbol | Unit | Value |
|---------------------------------------|--------------|------|-------|
| Maximum primary conductor temperature | $T_{B \max}$ | °C | 100 |

Stresses above these ratings may cause permanent damage.
Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 8

Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT - Edition 11 - Revision Date 2011/08/01
 - UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT - Edition 17 - Revision Date 2013/10/16
- For use only in complete equipment where the acceptability of the combination is determined by UL.LLC.

Ratings

| Parameter | Symbol | Unit | Value |
|---------------------------------|--------|---------|-------|
| Primary involved potential | | V AC/DC | 1000 |
| Max surrounding air temperature | T_A | °C | 70 |
| Primary current | I_P | A | 125 |

Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

- *These devices must be mounted in a suitable end-use enclosure.*
- *The terminals have not been evaluated for field wiring*
- *The products shall be used in a pollution degree 2*
- *Based on results of temperature test, in the end-use application a maximum of 100 °C can not be exceeded on the primary conductor.*

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

Insulation coordination

| Parameter | Symbol | Unit | Value | Comment |
|--|-------------|------|--------------------|---|
| RMS voltage for AC insulation test, 50 Hz, 1 min | U_d | kV | 4.3 | |
| Impulse withstand voltage 1.2/50 μ s | \hat{U}_w | kV | 7.8 | |
| Partial discharge extinction RMS voltage @ 10 pC | U_t | kV | 1.8 | |
| Clearance (pri. - sec.) | d_{cl} | mm | 8 | Shortest distance through air |
| Creepage distance (pri. - sec.) | d_{cp} | mm | 8 | Shortest path along device body |
| Case material flammability | - | -- | V0 | According to UL 94 |
| Application example | - | | 600 V CAT III PD2 | Reinforced insulation according to EN 50178 |
| Application example | - | | 300 V CAT III PD2 | Reinforced insulation according to EN 61010-1 |
| Application example | - | | 600 V CAT IV PD2 | Basic insulation according to EN 61010-1 |
| Application example | - | | 1000 V CAT III PD2 | Basic insulation according to EN 61010-1 |
| Application example | - | | | According to UL 508 |

Environmental and mechanical characteristics

| Parameter | Symbol | Unit | Min | Typ | Max | Comment |
|---|--------|------|-----|-----|------|---------|
| Ambient operating temperature | T_A | °C | -20 | | 70 | |
| Ambient storage temperature | T_s | °C | -40 | | 85 | |
| Relative humidity (non-condensing) | RH | % | | | | |
| Altitude above sea level | | m | | | 2000 | |
| Surrounding temperature according to UL | | °C | | | 70 | |
| Mass | m | g | | 120 | | |

Electrical data ATO-125-B1I-D16

At $T_A = 25\text{ °C}$, $R_{br} = 4\text{ }\Omega$, unless otherwise noted.

| Parameter | Symbol | Unit | Min | Value | Max | Comment |
|----------------------------------|-----------|----------|-----|-------|-----|--------------------------|
| Rated burden | R_{br} | Ω | | 4 | | |
| Rated primary current | I_{Pr} | A | | 125 | | |
| Rated extended primary current | I_{ePr} | A | | 150 | | |
| Rated short-time thermal current | I_{th} | kA | | 7.5 | | $60 \times I_{Pr}$ (1 s) |
| Rated dynamic current | I_{dyn} | kA | | 18.75 | | $2.5 \times I_{th}$ |
| Rated transformation ratio | k_{ra} | A/A | | 1000 | | |
| Rated secondary | I_{Sr} | mA | | 125 | | |
| Rated frequency | f_r | Hz | | 50/60 | | |

| Parameter | Symbol | Unit | Min | Typ | Max | Comment |
|--------------------------------------|-----------------|----------|------|-----|-----|---------|
| Frequency bandwidth (-3 dB) | BW | kHz | | 500 | | |
| Phase displacement | $\Delta\phi$ | ° | 0.5 | | 2.5 | |
| Temperature coefficient of I_{out} | TCI_{out} | ppm/k | | 60 | | |
| Coil inductance | L_S | H | | 4.5 | | |
| Coil resistance | R_S | Ω | | 24 | | |
| Ratio error | ε | % | -1 | | 1 | |
| Linearity error | ε_L | % | -0.1 | | 0.1 | |

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

Typical performance characteristics

Accuracy class 3 according to IEC 61869-2

At $T_A = 25\text{ }^{\circ}\text{C}$, frequency = 50 Hz, $R_{br} = 4\text{ }\Omega$, unless otherwise noted.

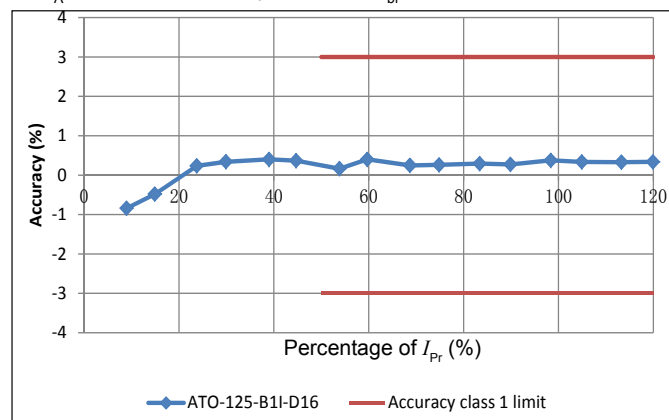


Figure 1: Accuracy vs. Percentage of I_{Pr}

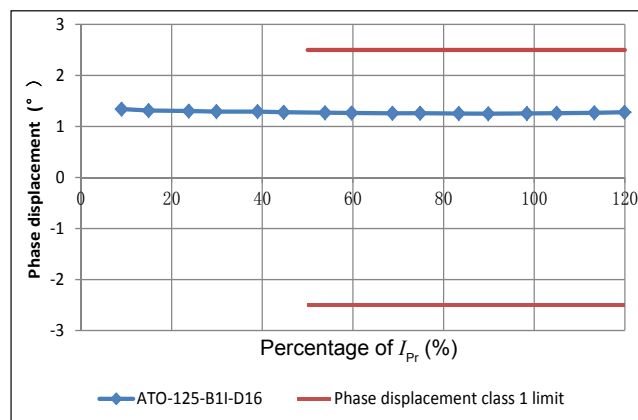


Figure 2: Phase shift vs. Percentage of I_{Pr}

| % of I_{Pr} | Ratio error | | | Phase displacement | | |
|---------------|-------------|-------|-------|--------------------|-------|-------|
| | 50 % | 100 % | 120 % | 50 % | 100 % | 120 % |
| Maximum | 3 % | 3 % | 3 % | 2.5° | 2.5° | 2.5° |
| Minimum | -3 % | -3 % | -3 % | -2.5° | -2.5° | -2.5° |

At $T_A = 25\text{ }^{\circ}\text{C}$, frequency = 60 Hz, $R_{br} = 4\text{ }\Omega$, unless otherwise noted.

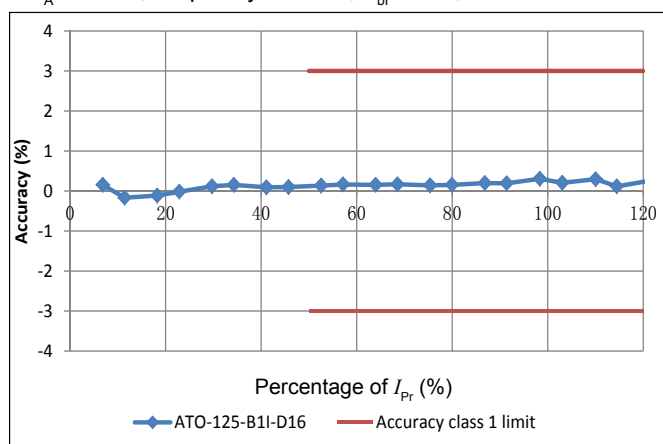


Figure 3: Accuracy vs. Percentage of I_{Pr}

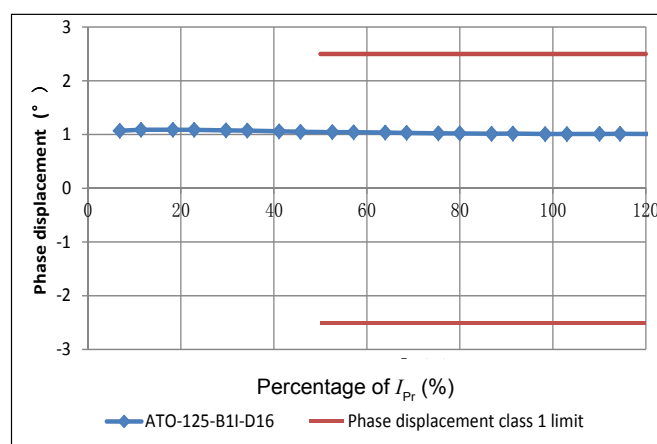


Figure 4: Phase displacement vs. Percentage of I_{Pr}

| % of I_{Pr} | Ratio error | | | Phase displacement | | |
|---------------|-------------|-------|-------|--------------------|-------|-------|
| | 50 % | 100 % | 120 % | 50 % | 100 % | 120 % |
| Maximum | 3 % | 3 % | 3 % | 2.5° | 2.5° | 2.5° |
| Minimum | -3 % | -3 % | -3 % | -2.5° | -2.5° | -2.5° |

Typical performance characteristics versus load resistance R_L

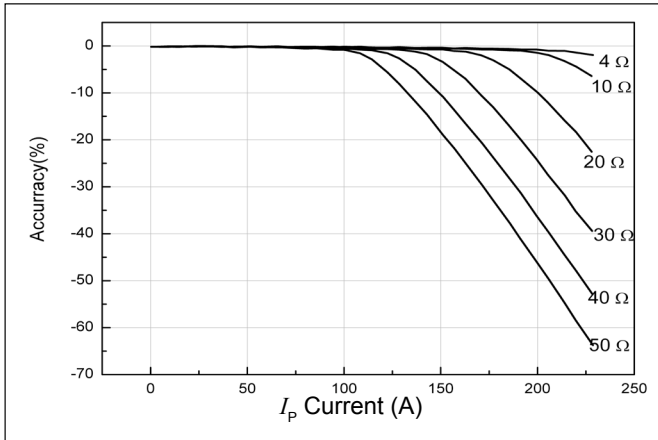


Figure 5: Accuracy vs. I_p Current @ 50 Hz

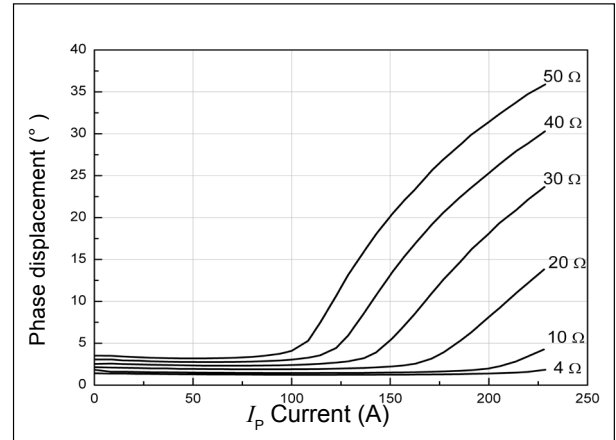


Figure 6: Phase displacement vs. I_p Current @ 50 Hz

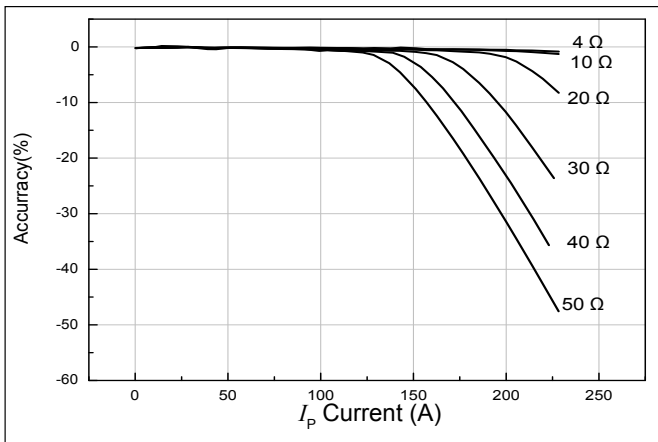


Figure 7: Accuracy vs. I_p Current @ 50 Hz

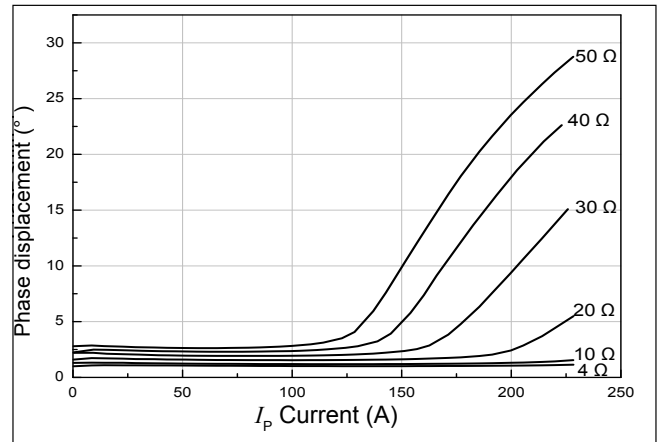


Figure 8: Phase displacement vs. I_p Current @ 60 Hz

Phase displacement compensation capacitance with different load resistance and frequency

| Load resistance (Ω) | 50 Hz Compensation capacitance (μF) | 60 Hz Compensation capacitance (μF) | Class 1 compliance |
|------------------------------|--|--|--------------------|
| 4.1 | 10 μF + 4.7 μF | 10 μF | OK |
| 5.6 | 10 μF + 1 μF | 4.7 μF + 3.3 μF | OK |
| 6.8 | 10 μF | 4.7 μF + 2 μF | OK |
| 7.5 | 6.8 μF + 2.2 μF | 4.7 μF + 1.5 μF | OK |
| 8.2 | 4.7 μF + 3.3 μF | 4.7 μF + 1 μF | OK |
| 9.1 | 6.8 μF + 1 μF | 4.7 μF + 0.68 μF | OK |
| 10 | 4.7 μF + 1.5 μF | 4.7 μF + 0.22 μF | OK |
| 12 | 4.7 μF + 1.5 μF | 2.2 μF + 2.2 μF | OK |
| 15 | 4.7 μF + 1 μF | 2.2 μF + 1.5 μF | OK |
| 20 | 4.7 μF | 3.3 μF | OK |

Typical phase displacement compensation

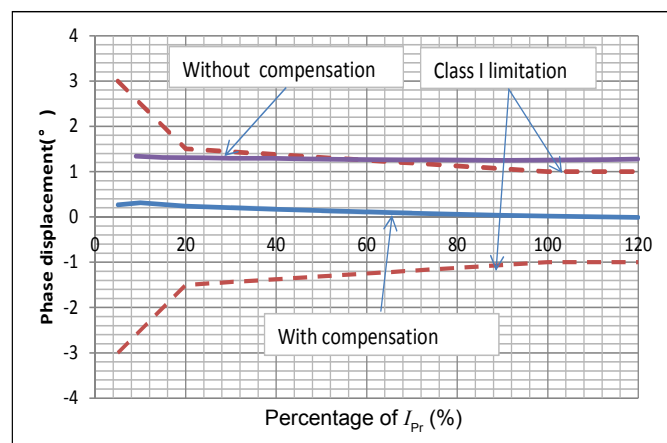


Figure 9: Compensation of *Phase displacement* @ 50 Hz

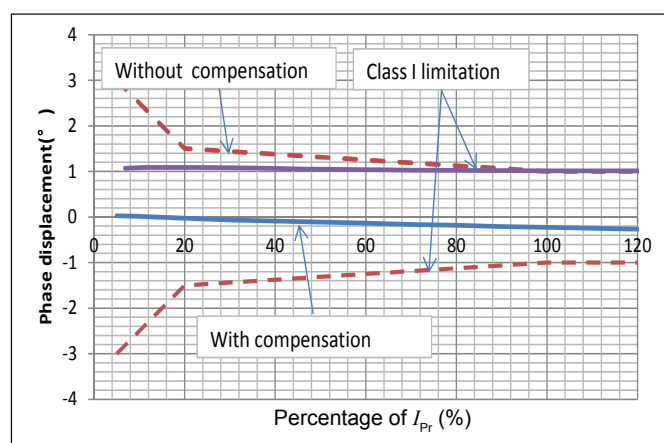


Figure 10 Compensation of *Phase displacement* @ 60 Hz

Performance parameters definition

Rated transformation ratio K_{ra}

Ratio of K_{ra} to the actual secondary voltage or current.

Ratio error ε

The current ratio error, expressed as a percentage is defined by the formula:

$$\varepsilon = \frac{k_{ra} I_s - I_p}{I_p} \times 100 \%$$

Where:

K_{ra} : is the rated transformation ratio

I_p : is the actual primary current

I_s : is the actual secondary current when I_p is flowing

Phase displacement $\Delta\phi$

The $\Delta\phi$ is the difference in phase between the primary current and the ideal secondary voltage phasors. The direction of the phasors being that the angle is 90 ° (leading) for an ideal Rogowski coil.

The phase displacement is said to be positive when the secondary voltage phasor leads the primary current phasor.

Linearity error ε_L

The linearity error ε_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed as a percentage of I_{pr} .

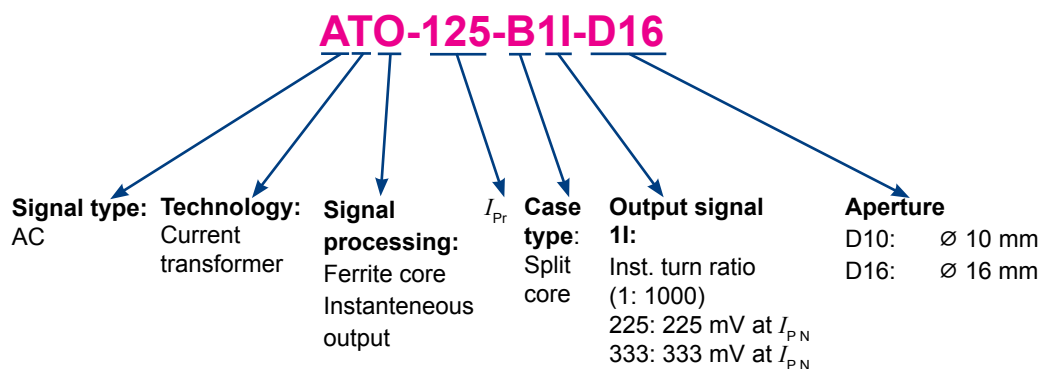
Rated short-time thermal current I_{th}

Maximum value of the primary current which a transformer will withstand for a specified short time without suffering harmful effects.

Rated dynamic current I_{dyn}

Maximum peak value of the primary current which a transformer will withstand, without being damaged electrically or mechanically by the resulting electromagnetic forces, the secondary winding being short-circuited.

ATO-125-B1I-D16 series: name and codification



Safety and warning notes

In order to guarantee safe operation of the transducer and to be able to make proper use of all features and functions, please read these instructions thoroughly!

Safe operation can only be guaranteed if the transducer is used for the purpose it has been designed for and within the limits of the technical specifications.

Ensure you get up-to-date technical information that can be found in the latest associated datasheet under www.lem.com.



Caution! Risk of danger

Ignoring the warnings can lead to serious injury and/or cause damage! The electric measuring transducer may only be installed and put into operation by qualified personnel that have received an appropriate training.

The corresponding national regulations shall be observed during installation and operation of the transducer and any electrical conductor.

The transducer shall be used in electric/electronic equipment with respect to applicable standards and safety requirements and in accordance with all the related systems and components manufacturers' operating instructions.

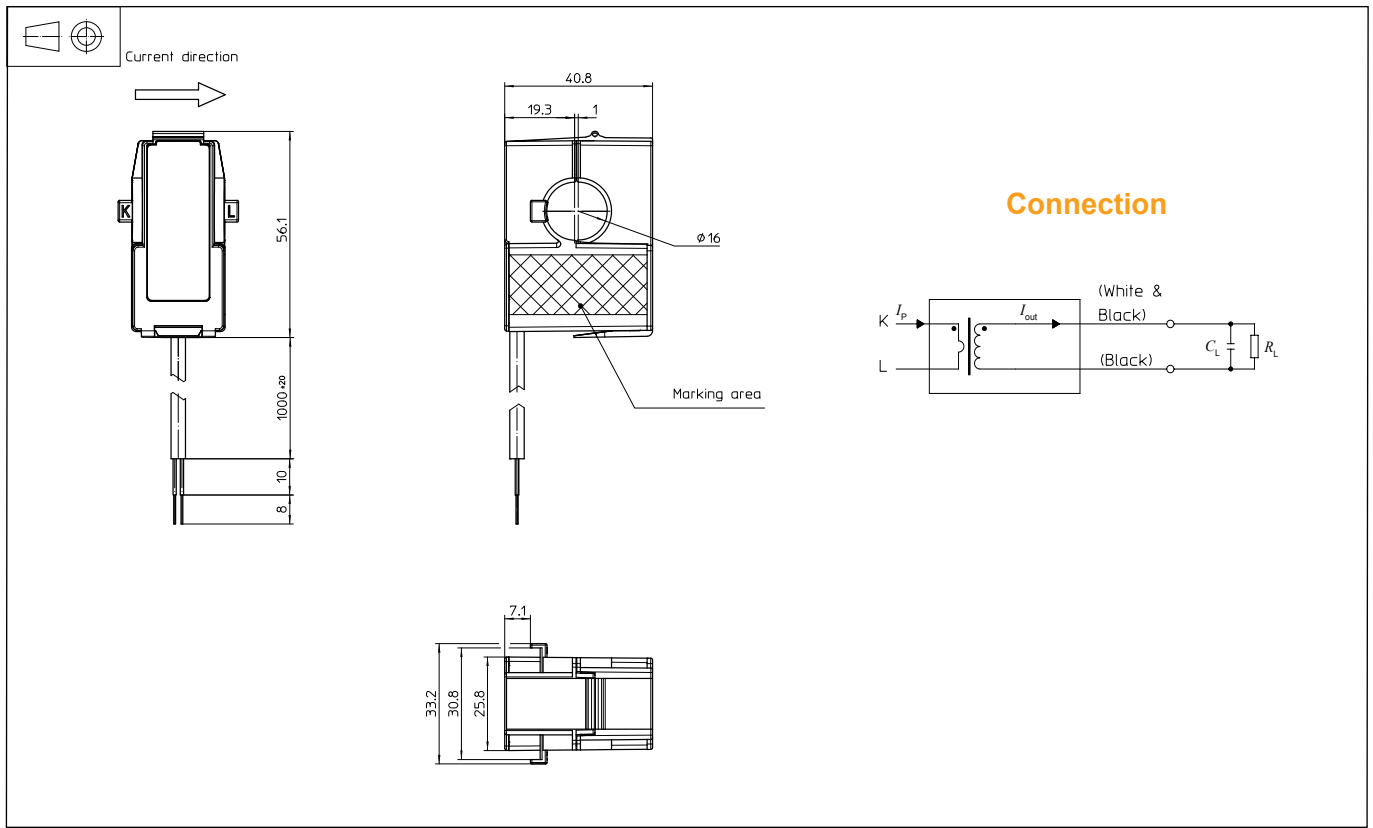


Caution! Risk of electrical shock

When operating the transducer, certain parts of the module may carry hazardous live voltage (e.g. primary conductor). The user shall ensure to take all measures necessary to protect against electrical shock. The transducer is a build-in device containing conducting parts that shall not be accessible after installation. A protective enclosure or additional insulation barrier may be necessary. Installation and maintenance shall be done with the main power supply disconnected except if there are no hazardous live parts in or in close proximity to the system and if the applicable national regulations are fully observed.

Safe and trouble-free operation of this transducer can only be guaranteed if transport, storage and installation are carried out correctly and operation and maintenance are carried out with care.

Dimensions (in mm)



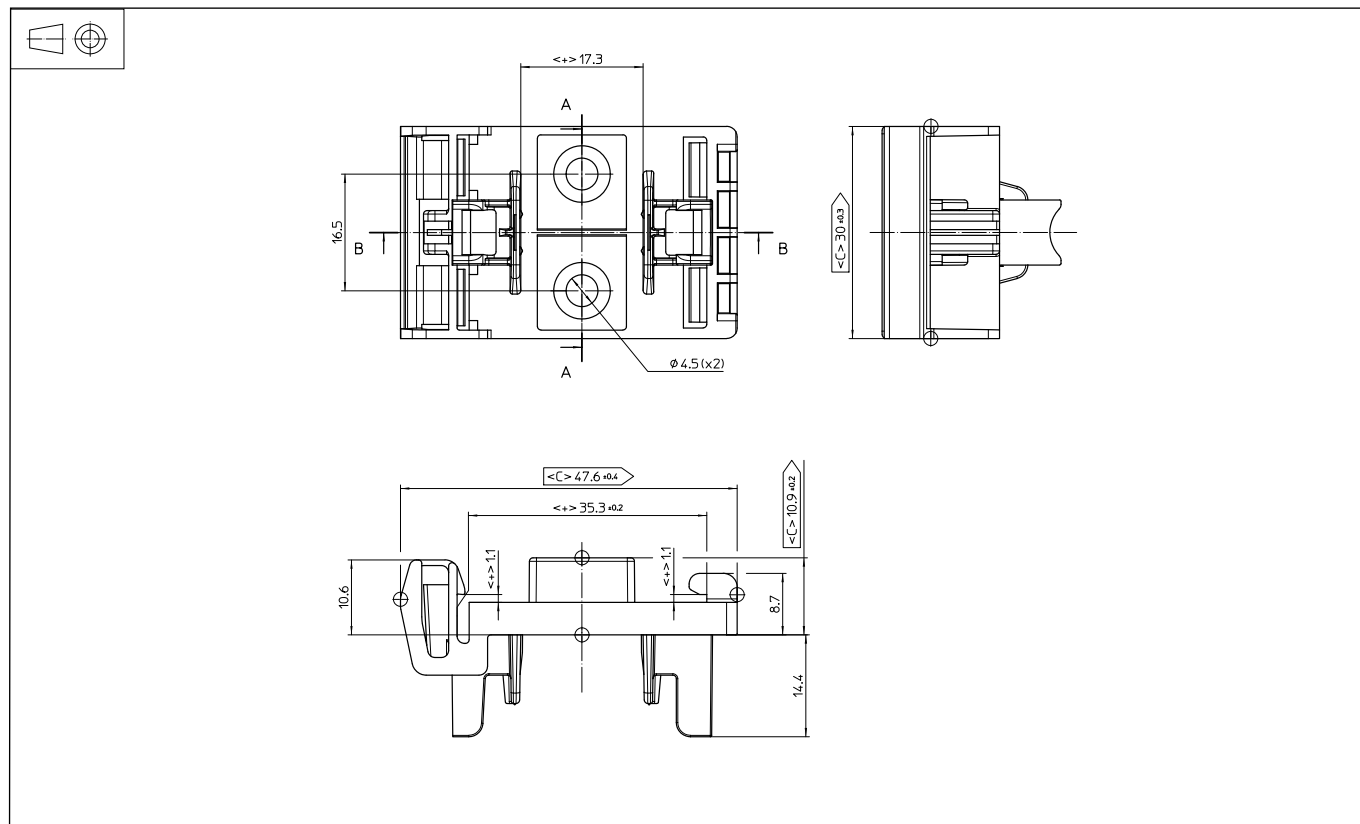
Mechanical characteristics

- General tolerance ± 0.5 mm
- Primary aperture $\varnothing 16$ mm
- Fastening Cable tie
- Output cable length 1 m

Remarks

- Attention: contact areas (air gap) must be kept clean (particle free) to ensure proper performance
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: www.lem.com Products/Product Documentation.

DIN RAIL ADAPTOR (additional part option) dimensions (in mm)



Mechanical characteristics

- General tolerance ± 0.4 mm
- Fastening 1.5 N·m

Remarks

- Attention: contact areas (air gap) must be kept clean (particle free) to ensure proper performance
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: [Products/Product Documentation](#).